Approachability of Convex Sets in "Some" Absorbing Games

Rida Laraki
CNRS, LAMSADE (Dauphine) and École Polytechnique

Joint work with

Janos Flesch and Vianney Perchet

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- Definitions and Notations
- Blackwell Type Conditions
 - Generalized Quitting Games
 - Application to Big Match Type 1
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 - One absorbing action, one non-absorbing action
 - General Case

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- Blackwell assumed that outcomes are vectorial payoffs $g_t \in \mathbb{R}^d$ and considers the problem where the DM aims to guarantee that the expected average payoff $\mathrm{E}[\frac{1}{T}\sum_{t=1}^T g(i_t,j_t)]$ approaches some convex target set $\mathcal{C} \subset \mathbb{R}^d$, for T large enough.

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• Blackwell also proved that a convex set is either approchable or excludable.

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Vieille, [Hart & Mas-Colell], Spinat, Lehrer, Dawid, Renault & Tomala [As Soulaimani, Quincampoix & Sorin], Perchet, [Lehrer & Solan] Rakhlin, [Sridharan & Tewari], [Perchet & Quincampoix], Lovo, Horner & Tomala [Foster & Vohra], [Fudenberg & Levine], [Sandroni, Smorodinsky & Vohra] [Hart & Mas-Colell], [Cesa-Bianchi & Lugosi], [Benaim, Hofbauer & Sorin]

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Quitting Games

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Sets of actions:

Pure actions of player 1 (the decision maker): $\mathbf{I} = \mathcal{I} \times \mathcal{I}^*$ Pure actions of player 2 (nature or advisory): $\mathbf{J} = \mathcal{J} \times \mathcal{J}^*$. Mixed actions of P1 $\mathbf{x} \in \Delta(\mathcal{I} \times \mathcal{I}^*)$, $\mathbf{x} \in \Delta(\mathcal{I})$, $\mathbf{x}^* \in \Delta(\mathcal{I}^*)$, Mixed actions of P2 $\mathbf{y} \in \Delta(\mathcal{I} \times \mathcal{I}^*)$, $\mathbf{y} \in \Delta(\mathcal{I})$, $\mathbf{y}^* \in \Delta(\mathcal{I}^*)$. Positive measures $\alpha \in \mathcal{M}(\mathbf{I})$ and $\beta \in \mathcal{M}(\mathbf{I})$.

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Vectorial payoffs

$$g(i,j) \in \mathbb{R}^d$$
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Target set (to be approached by player 1)

A closed and convex set $\mathcal{C} \subset \mathbb{R}^d$.

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Restrictions

If $\mathcal{J}^* = \emptyset$ then the game is a Big-match of type I. If $\mathcal{I}^* = \emptyset$ then the game is a Big-match of type II.

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- If $i_t \in \mathcal{I}$ and $j_t \in \mathcal{J}$, the game is not absorbed: the payoff of stage t is g_t , and we move to stage t+1.
- Player 1 wants to approach the set C, player 2 wants to avoid C.

Uniform Approachability

 $\forall \varepsilon > 0$, player 1 has a strategy σ such that after some stage $T \in \mathbb{N}$, $\overline{g}_T = \mathbb{E}_{\sigma,\tau}[\frac{1}{T}\sum_{t=1}^T g_t]$ is ε -close to \mathcal{C} , no matter the strategy τ of player 2.

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We will study the following stronger notion:

$$\begin{aligned} \forall \varepsilon > 0, \ \exists \theta_{\varepsilon} > 0 \text{ s.t. } \forall \theta = \{\theta_{s}\}_{s \in \mathbb{N}^{*}} \in \Delta(\mathbb{N}^{*}) \text{ satisfying} \\ \|\theta\|_{2} \leq \theta_{\varepsilon}, \ \exists \sigma, \ \forall \tau \ d_{\mathcal{C}} \Big(\mathbb{E}_{\sigma, \tau} \big[\sum_{t=1}^{\infty} \theta_{t} g_{t} \big] \Big) \leq \varepsilon. \end{aligned}$$

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Blackwell condition holds:

$$\forall \mathbf{y} = qL + (1-q)R, \exists \mathbf{x} = (1-q)T + qB : g(\mathbf{x}, \mathbf{y}) = 0$$

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Notations

• g is extended multi-linearly to the set of measures on $\mathcal{M}(\mathbf{J})$ and $\mathcal{M}(\mathbf{J})$:

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 We also extend the probability of absorption and the expected absorption payoffs:

$$p^{\star}(\alpha,\beta) = \sum_{i \in I} \alpha_i \beta_j - \sum_{i \notin \mathcal{I}^{\star}} \sum_{i \notin \mathcal{I}^{\star}} \alpha_i \beta_j$$

and

$$g^{\star}(\alpha, \beta) = g(\alpha, \beta) - \sum_{i \neq T^{\star}} \sum_{j \neq T^{\star}} \alpha_{i} \beta_{j} g(i, j).$$

The Conditions

Sufficient condition : SC

$$\max_{\mathbf{y} \in \Delta(\mathbf{J})} \inf_{\mathbf{x} \in \Delta(\mathbf{I})} \inf_{\alpha \in \mathcal{M}(\mathbf{I})} \sup_{\beta \in \mathcal{M}(\mathbf{J})} d_{\mathcal{C}}\Big(\frac{g(\mathbf{x}, \mathbf{y}) + g^{\star}(\alpha, \mathbf{y}) + g^{\star}(\mathbf{x}, \beta)}{1 + \rho^{\star}(\alpha, \mathbf{y}) + \rho^{\star}(\mathbf{x}, \beta)}\Big) = 0 \quad (1)$$

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Non-necessary, non-sufficient condition:

$$\max_{\mathbf{y} \in \Delta(\mathbf{J})} \min_{\mathbf{x} \in \Delta(\mathbf{I})} \sup_{\beta \in \mathcal{M}(\mathbf{J})} \inf_{\alpha \in \mathcal{M}(\mathbf{I})} d_{\mathcal{C}}\left(\frac{g(\mathbf{x}, \mathbf{y}) + g^{\star}(\alpha, \mathbf{y}) + g^{\star}(\mathbf{x}, \beta)}{1 + p^{\star}(\alpha, \mathbf{y}) + p^{\star}(\mathbf{x}, \beta)}\right) = 0 \quad (2)$$

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Necessary condition: NC

$$\max_{\mathbf{y} \in \Delta(\mathbf{J})} \sup_{\beta \in \mathcal{M}(\mathbf{J})} \min_{\mathbf{x} \in \Delta(\mathbf{I})} \inf_{\alpha \in \mathcal{M}(\mathbf{I})} d_{\mathcal{C}} \left(\frac{g(\mathbf{x}, \mathbf{y}) + g^{\star}(\alpha, \mathbf{y}) + g^{\star}(\mathbf{x}, \beta)}{1 + p^{\star}(\alpha, \mathbf{y}) + p^{\star}(\mathbf{x}, \beta)} \right) = 0 \quad (3)$$

Main Results for Weak Approachability

Theorem

SC (condition 1) is sufficient for W-approachability.
NC (condition 3) is necessary for W-approachability.
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Lemma

Condition SC is equivalent to

(1)
$$\exists (x_0, x_0^*, \gamma_0) \in \Delta(\mathcal{I}) \times \Delta(\mathcal{I}^*) \times (0, 1]$$
 such that

$$g(x_0^*, j) \in \mathcal{C}, \ \forall j \in \mathcal{J}$$

and $g((1 - \gamma_0)x_0 + \gamma_0x_0^*, j^*) \in \mathcal{C}, \forall j^* \in \mathcal{J}^*$

or

(2)
$$\forall \varepsilon, \ \forall y \in \Delta(\mathcal{J}), \exists (x, x^*, \gamma) \in \Delta(\mathcal{I}) \times \Delta(\mathcal{I}^*) \times [0, 1]$$
 such that:

$$g((1-\gamma)x + \gamma x^*, y) \in \mathcal{C} + \varepsilon \mathcal{B}(0, 1)$$

and $g(x, j^*) \in \mathcal{C} + \varepsilon \mathcal{B}(0, 1), \forall j^* \in \mathcal{J}^*$

$$\exists (x_0, x_0^*, \gamma_0) \in \Delta(\mathcal{I}) \times \Delta(\mathcal{I}^*) \times (0, 1]$$
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- The game is absorbed at each stage with proba γ_0 or 1 (depending on P2).
- By condition SC, if the game is absorbed, the payoff is necessarily in C.

$$\exists (x_0, x_0^*, \gamma_0) \in \Delta(\mathcal{I}) \times \Delta(\mathcal{I}^*) \times (0, 1]$$
 such that $g(x_0^*, j) \in \mathcal{C}, \ \forall j \in \mathcal{J}$ and $g((1 - \gamma_0)x_0 + \gamma_0x_0^*, j^*) \in \mathcal{C}, \forall j^* \in \mathcal{J}^*$

- Player 1 play i.i.d according to $(1 \gamma_0)x_0 + \gamma_0x_0^* \in \Delta(I)$.
- The game is absorbed at each stage with proba γ_0 or 1 (depending on P2).
- By condition SC, if the game is absorbed, the payoff is necessarily in C.
- Consequently.

$$d\left(\mathbb{E}\left[\overline{g}_{\theta}\right],\mathcal{C}\right) \leq \sum_{s=1}^{\infty} (1-\gamma_0)^s \theta_s M \leq \frac{1-\gamma_0}{\sqrt{2\gamma_0-\gamma_0^2}} \|\theta\|_2 M$$



$$\begin{split} \forall \varepsilon, \ \forall y \in \Delta(\mathcal{J}), \exists (x, x^*, \gamma) \in \Delta(\mathcal{I}) \times \Delta(\mathcal{I}^*) \times [0, 1] \text{ such that:} \\ (1 - \gamma) g(x, y) + \gamma g(x^*, y) \in \mathcal{C} + \varepsilon \mathcal{B}(0, 1) \\ \text{and } g(x, j^*) \in \mathcal{C} + \varepsilon \mathcal{B}(0, 1), \forall j^* \in \mathcal{J}^* \end{split}$$

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- ullet The strategy of player 1 at stage au (history dependent) is defined as:

$$\gamma_{\tau}[k_{\tau}]x^*[k_{\tau}] + (1 - \gamma_{\tau}[k_{\tau}])x[k]$$

where:

$$\gamma_{\tau}[k_{\tau}] := \frac{\gamma[k_{\tau}]\theta_{\tau}}{(1 - \gamma[k_{\tau}])\sum_{s=\tau}^{\infty}\theta_{s} + \gamma[k_{\tau}]\theta_{\tau}}$$



Necessary Condition

Condition NC (condition 3)

$$\max_{\mathbf{y} \in \Delta(\mathbf{J})} \sup_{\beta \in \mathcal{M}(\mathbf{J})} \min_{\mathbf{x} \in \Delta(\mathbf{I})} \inf_{\alpha \in \mathcal{M}(\mathbf{I})} d_{\mathcal{C}} \Big(\frac{g(\mathbf{x}, \mathbf{y}) + g^{\star}(\alpha, \mathbf{y}) + g^{\star}(\mathbf{x}, \beta)}{1 + p^{\star}(\alpha, \mathbf{y}) + p^{\star}(\mathbf{x}, \beta)} \Big) = 0$$

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NC is necessary for weak approachability in generalized quitting games.

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Theorem

NC is necessary for weak approachability in generalized quitting games.

If not, player 2 just play at every stage y perturbed by $\beta.$ This allows him to exclude $\mathcal{C}.$

Lemma

In Big-Match of type I, SC and NC are equivalent to Blackwell condition:

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$\mathsf{Theorem}$

Blackwell condition is necessary and sufficient for weak approachability in BM games of type 1.

Introduction to Blackwell Approachability Definitions and Notati Generalized Quitting Games Application to Big Match Type 1

Uniform Approachability in Big Match Type 1

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Here, Blackwell condition is satisfied for $C = \{0\}$.

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- Denote by q^* the probability, that play eventually absorbs. Since

$$u(\sigma,\tau) = \frac{1}{2}q^* - \frac{1}{2}(1-q^*) = q^* - \frac{1}{2},$$

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- Take t large so that the proba q_t that play absorbs before t is at least $\frac{3}{10}$.
- Let τ' the strategy $(\frac{1}{2}, \frac{1}{2})$ at all periods before period t and L after. Then

$$u(\sigma,\tau')\geq \tfrac{1}{2}q_t\geq \tfrac{3}{20}>\tfrac{1}{10},$$

Theorem

In BM games of type 1, a convex set is either W-approachable or W-excludable.

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Sorin example lies in \mathbb{R}^2 :

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The set $C = \{(x,y) : x \ge \frac{3}{8}, y \ge \frac{3}{8}\}$ is neither uniformly approchable nor uniformly excludable.

Introduction to Blackwell Approachability Definitions and Notati Generalized Quitting Games Application to Big Match Type 1

Approachability in Big Match of Type 2

Theorem

Condition 1 and Condition 2 are not necessary for weak approachability in BM games of type 2.

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Lemma

In Big-Match games of type II, SC (condition 1) is equivalent to

$$\forall y \in \Delta(\mathcal{J}), \exists x \in \Delta(\mathcal{I}), g(x, y) \in \mathcal{C} \text{ and } g(x, j^*) \in \mathcal{C}, \forall j^* \in \mathcal{J}^*$$

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If $y \in \Delta(\mathcal{J})$ is predicted, P1 plays $x \in \Delta(\mathcal{I})$. And this strategy must remain "good" even if player 2 decides to quit the game.



- Introduction to Blackwell Approachability
- Definitions and Notations
- 3 Blackwell Type Conditions
 - Generalized Quitting Games
 - Application to Big Match Type 1
 - Application to Big Match Type 2
- Viability Type Conditions in Big Match of Type 2
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If $\mathcal C$ is weakly approchable, \exists a measurable mapping $\xi:[0,1]\to\Delta(I)$ such that for almost every $t\in[0,1]$,

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• $\forall \varepsilon > 0$, $\exists N_{\varepsilon}$, s.t. $\forall N \geq N_{\varepsilon}$, $\exists \{x^{N,\varepsilon}(k), k = 1, ..., N\}$, s.t. $\forall t \in [0, 1]$:

$$\sum_{k=1}^{[Nt]} \frac{g_R(x^{N,\varepsilon}(k))}{N} + (1 - \frac{[Nt]}{N})g_L^*(x^{N,\varepsilon}([Nt]+1)) \in \mathcal{C} + \varepsilon \mathcal{B}(0,1),$$

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• Defining $\xi^{N,\varepsilon}(s) = x^{N,\varepsilon}([sN]+1)$, we obtain that $\forall t \in [0,1]$:

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• We tend N to infinity and ε to zero.



Theorem

If there is a continuous mapping $\xi:[0,1]\to\Delta(I)$ such that for every $t\in[0,1]$,

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- Now we divide each time interval of length 1/N on a large block of length L in which player 1 plays an i.i.d strategies $\xi(s)$.
- By the law of large numbers, on the block L, the average payoff if player 2 plays always R is $g_R(\xi(s))$.

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• Find a C^1 function ξ (where $\xi(s)$ = proba of T at time s) s.t. $\forall t$:

$$\int_0^t (\xi(s)p - (1 - \xi(s))ds + (1 - t)\xi(t) = 0,$$

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$$\begin{array}{c|cccc} & L & R \\ T & 1^* & p \\ B & 0^* & -1 \end{array}$$

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• That is, player 1 starts at $x_0 = \mathbf{B}$ and then, with time, he increases slightly the probability of \mathbf{T} until reaching $x_1 = \frac{1}{a}\mathbf{T} + (1 - \frac{1}{a})\mathbf{B}$.

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- Condition 2 is not necessary nor sufficient for W-approachability.

If player 2 has many absorbing actions, but one non-absorbing action R, then:

Theorem

If \exists a continuous mapping $\xi : [0,1] \to \Delta(\mathbf{I})$ such that $\forall t \in [0,1]$ and $\forall j^* \in \mathcal{J}^*$,

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Without absorption, this is Vieille's differential game characterization for W-approachability.

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Theorem

Thanks to the organizers. It is impossible to do a better conference!